

# TABLE OF CONTENTS

Series editor's preface	v
Preface	xi
<b>Chapter 1. Preliminary information</b>	
1.1 On the style of presentation	1
1.2 Some facts from general topology	1
1.3 Gluings	4
1.4 Polyhedra and complexes	5
1.5 Fundamental groups	9
1.6 An algorithm for the calculation of the fundamental group	10
1.7 The second homotopy group and the first homology group	15
1.8 Manifolds	15
1.9 Fibrations and coverings	22
1.10 General position and transversality	23
1.11 Handles	27
1.12 Algorithmic problems	30
1.13 Sources of additional information	31
<b>Chapter 2. Surfaces</b>	
2.1 Examples of surfaces	33
2.2 Classification of surfaces	35
2.3 Homotopy equivalence of surfaces	41
2.4 Cutting-gluing surgery	49
2.5 Applications of cutting-gluing surgery	60
2.6 The Dehn lemma and the loop theorem	64
2.7 Algorithmic problems	69
<b>Chapter 3. The homeotopy group of a surface</b>	
3.1 The homeotopy group	71
3.2 Twists	71
3.3 The homeotopy group of a disc modulo boundary	73
3.4 The braid group	73
3.5 The pure braid group	77
3.6 The homeotopy groups of a disc with holes	79
3.7 The homeotopy group of an arbitrary surface is generated by twists	81
3.8 Finite generation of the homeotopy group of an arbitrary surface by twists	86
3.9 The homeotopy group of a handlebody	93
3.10 Comments	107

<b>Chapter 4. The presentation of three-dimensional manifolds by the identification of faces of polyhedra</b>	
4.1 Three-dimensional manifolds with conic singularities	109
4.2 The criterion of the absence of singularities	112
4.3 Lens spaces	114
4.4 Manifolds of genus 1	120
<b>Chapter 5. Heegaard splittings and Heegaard Diagrams</b>	
5.1 The Heegaard splitting	123
5.2 Stable equivalence of Heegaard splittings	125
5.3 Heegaard diagrams	129
5.4 Equivalent diagrams	130
5.5 Normalized diagrams	132
5.6 Wave transformation of the Heegaard diagram	135
5.7 The structure of Heegaard diagrams of genus 2	137
5.8 On the enumeration of three-dimensional manifolds	142
<b>Chapter 6. Algorithmic recognition of the sphere</b>	
6.1 On the formulation of the classification problem for three-dimensional manifolds	145
6.2 The algorithm for recognition of a sphere $S^3$ in the class of manifolds of genus 2	146
6.3 Comments to chapters 5.6	157
<b>Chapter 7. Connected sums</b>	
7.1 The properties of connected summation	159
7.2 Irreducible and prime manifolds	160
7.3 The theory of normal surfaces	165
7.4 The existence of decomposition into prime summands	171
7.5 Uniqueness of decomposition into prime summands	174
<b>Chapter 8. Knots and links</b>	
8.1 Basic Definitions	179
8.2 Distributive groupoids in the knot theory	182
8.3 The Conway approach	192
8.4 Special realizations of the invariant $w$	202
8.5 The linking coefficient	205
<b>Chapter 9. Surgery Along Links</b>	
9.1 Integral surgery and three-dimensional manifolds	207
9.2 Surgery along framed links and cobordism	209

9.3	The Kirby calculus	211
9.4	Even surgery	215
9.5	Presentations of homology spheres	221
9.6	On Heegaard diagrams of homology spheres	226
9.7	Sources and comments	228
<b>Chapter 10. Seifert Manifolds</b>		
10.1	The definition of a Seifert manifold	229
10.2	The base of a Seifert manifold	232
10.3	Seifert manifolds without singular fibers	233
10.4	Seifert manifolds with singular fibers	237
10.5	The Euler number and the fiberwise classification of Seifert manifolds	238
10.6	The fundamental group of a Seifert manifold	241
10.7	Seifert manifolds with boundary	244
10.8	Incompressibility of the boundary	244
10.9	Irreducibility of Seifert manifolds with boundary	245
10.10	Fiberwise character of annuli with fiberwise boundaries	245
10.11	Fiberwise nature of essential annuli	247
10.12	Large Seifert manifolds	255
10.13	Fiberwise nature of incompressible tori	256
10.14	Topological classification of large closed Seifert manifolds	258
10.15	Small Seifert manifolds with finite fundamental groups	259
10.16	Small Seifert manifolds with infinite fundamental groups	267
<b>Chapter 11. Class <math>\mathcal{H}</math></b>		
11.1	Definition and the simplest properties of class $\mathcal{H}$	271
11.2	Rough and thin tori	274
11.3	Classification of class $\mathcal{H}$ manifolds	276
11.4	Class $\mathcal{H}$ and iterated torus links	283
<b>Chapter 12. The Haken Method</b>		
12.1	Normal surfaces as solutions of a system of equations	287
12.2	Fundamental sets of solutions	290
12.3	Geometric summation	291
12.4	The Haken algorithm	294
12.5	An example of stability	295
12.6	An algorithm for the recognition of the trivial knot	297
<b>Comments on the Figures</b>		299
<b>References</b>		323
<b>Index</b>		327