

1 Polyhedra. Simplicial Complexes. Homologies

1.1	Polyhedra	1
1.1.1	Introductory Remarks	1
1.1.2	The Concept of an n -Dimensional Simplex Barycentric Coordinates	5
1.1.3	Polyhedra. Simplicial Subdivisions of Polyhedra. Simplicial Complexes	8
1.1.4	Examples of Polyhedra	10
1.1.5	Barycentric Subdivision	14
1.1.6	Visual Material	16
1.2	Simplicial Homology Groups of Simplicial Complexes (Polyhedra)	18
1.2.1	Simplicial Chains	18
1.2.2	Chain Boundary	23
1.2.3	The Simplest Properties of the Boundary Operator Cycles. Boundaries	26
1.2.4	Examples of Calculations of the Boundary Operator	27
1.2.5	Simplicial Homology Groups	29
1.2.6	Examples of Calculations of Homology Groups. Homologies of Two-dimensional Surfaces	32
1.2.7	Visual Material	46
1.3	General Properties of Simplicial Homology Groups	49
1.3.1	Incidence Matrices	49
1.3.2	The Method of Calculation of Homology Groups Using Incidence Matrices	50

1.3.3	“Traces” of Cell Homologies Inside Simplicial Ones	56
1.3.4	Chain Homotopy. Independence of Simplicial Homologies of a Polyhedron of the Choice of Triangulation	59
1.3.5	Visual Material	65

2 Low-Dimensional Manifolds

2.1 Basic Concepts of Differential Geometry	75
2.1.1 Coordinates in a Region.	
Transformations of Curvilinear Coordinates	75
2.1.2 The Concept of a Manifold. Smooth Manifolds.	
Submanifolds and Ways of Defining Them. Manifolds with Boundary. Tangent Space and Tangent Bundle	79
2.1.3 Orientability and Non-Orientability. The Differential of a Mapping. Regular Values and Regular Points. Embeddings and Immersions of Manifolds.	
Critical Points of Smooth Functions on Manifolds.	
Index of Nondegenerate Critical Points and Morse Functions	85
2.1.4 Vector and Covector Fields. Integral Trajectories.	
Vector Field Commutators. The Lie Algebra of Vector Fields on a Manifold	91
2.1.5 Visual Material	95
2.2 Visual Properties of One-Dimensional Manifolds	98
2.2.1 Isotopies, Frames	98
2.2.2 Visual Material	102
2.3 Visual Properties of Two-Dimensional Manifolds	111
2.3.1 Two-Dimensional Manifolds with Boundary	111
2.3.2 Examples of Two-Dimensional Manifolds	113
2.3.3 Modelling of a Projective Plane in a Three-Dimensional Space	115
2.3.4 Two Series of Two-Dimensional Closed Manifolds	120

2.3.5	Classification of Closed 2-Manifolds	125
2.3.6	Inversion of a Two-Dimensional Sphere	128
2.3.7	Visual Material	130
2.4	Cohomology Groups and Differential Forms	135
2.4.1	Differential 1-Forms on a Smooth Manifold	135
2.4.2	Closed and Exact Forms on a Two-Dimensional Manifold	136
2.4.3	An Important Property of Cohomology Groups	138
2.4.4	Direct Calculation of One-Dimensional Cohomology Groups of One-Dimensional Manifolds	139
2.4.5	Direct Calculation of One-Dimensional Cohomology Groups of a Plane, a Two-Dimensional Sphere and a Torus	141
2.4.6	Direct Calculation of One-Dimensional Cohomology Groups of Oriented Surfaces, i.e. Spheres with Handles	148
2.4.7	An Algorithm for Recognition of Two-Dimensional Manifolds. Elements of Two-Dimensional Computer Geometry	152
2.4.8	Calculation of One-Dimensional Cohomologies of a Surface Using Triangulation	154
2.4.9	Visual Material	154
2.5	Visual Properties of Three-Dimensional Manifolds	159
2.5.1	Heegaard Splittings (or Diagrams)	159
2.5.2	Examples of Three-Dimensional Manifolds	162
2.5.3	Equivalence of Heegaard Splittings	164
2.5.4	Spines	165
2.5.5	Special Spines	168
2.5.6	Filtration of 3-Manifolds with Respect to Matveev's Complexity	170
2.5.7	Simplification of Special Spines	173
2.5.8	The Use of Computers in Three-Dimensional Topology. Enumeration of Manifolds in Increasing Order of Complexity	177
2.5.9	Matveev's Complexity of 3-Manifolds and Simplex Glueings	184
2.5.10	Visual Material	188

3	Visual Symplectic Topology and Visual Hamiltonian Mechanics	
3.1	Some Concepts of Hamiltonian Geometry	193
3.1.1	Hamiltonian Systems on Symplectic Manifolds	193
3.1.2	Involutive Integrals and Liouville Tori	196
3.1.3	Momentum Mapping of an Integrable System	200
3.1.4	Surgery on Liouville Tori at Critical Energy Values	200
3.1.5	Visual Material	204
3.2	Qualitative Questions of Geometric Integration of Some Differential Equations. Classification of Typical Surgeries of Liouville Tori of Integrable Systems with Bott Integrals	208
3.2.1	Nondegenerate (Bott) Integrals	208
3.2.2	Classification of Surgeries of Bott Position on Liouville Tori	210
3.2.3	The Topological Structure of Critical Energy Levels at a Fixed Second Integral	215
3.2.4	Examples from Mechanics. The Equations of Motion of a Rigid Body. The Poisson Sphere. Geometrical Interpretation of Mechanical Systems	216
3.2.5	An Example of an Investigation of a Mechanical System. The Liouville System on the Plane	219
3.2.6	The Liouville System on the Sphere	220
3.2.7	Inertial Motion of a Gyrostat	221
3.2.8	The Case of Chaplygin-Sretensky	223
3.2.9	The Case of Kovalevskaya	224
3.2.10	Visual Material	225
3.3	Three-Dimensional Manifolds and Visual Geometry of Isoenergy Surfaces of Integrable Systems	231
3.3.1	A One-Dimensional Graph as a Hamiltonian Diagram	231
3.3.2	What Familiar Manifolds Are Encountered Among Isoenergy Surfaces?	234

3.3.3	The Simplest Isoenergy Surfaces (with Boundary)	243
3.3.4	Any Isoenergy Surface of an Integrable Nondegenerate System Falls into the Sum of Five (or Two) Types of Elementary Bricks	244
3.3.5	New Topological Properties of the Isoenergy Surfaces Class	246
3.3.6	One Example of a Computer Use in Symplectic Topology	249
3.3.7	Visual Material	252

4 Visual Images in Some Other Fields of Geometry and Its Applications

4.1	Visual Geometry of Soap Films. Minimal Surfaces	255
4.1.1	Boundaries Between Physical Media. Minimal Surfaces	255
4.1.2	Some Examples of Minimal Surfaces	258
4.1.3	Visual Material	260
4.2	Fractal Geometry and Homeomorphisms	264
4.2.1	Various Concepts of Dimension	264
4.2.2	Fractals	267
4.2.3	Homeomorphisms	268
4.2.4	Visual Material	276
4.3	Visual Computer Geometry in the Number Theory	284

Appendix 1 Visual Geometry of Some Natural and Nonholonomic Systems

1.1	On Projection of Liouville Tori in Systems with Separation of Variables	293
1.2	What Are Nonholonomic Constraints?	295
1.3	The Variety of Manifolds in the Suslov Problem	297

Appendix 2 Visual Hyperbolic Geometry

2.1	Discrete Groups and Their Fundamental Region	300
2.2	Discrete Groups Generated by Reflections in the Plane . .	301
2.3	The Gram Matrix and the Coxeter Scheme	303
2.4	Reflection-Generated Discrete Groups in Space	303
2.5	A Model of the Lobachevskian Plane	306
2.6	Convex Polygons on the Lobachevskian Plane	308
2.7	Coxeter Polygons on the Lobachevskian Plane	309
2.8	Coxeter Polyhedra in the Lobachevskian Space	310
2.9	Discrete Groups of Motions of Lobachevskian Space and Groups of Integer-Valued Automorphisms of Hyperbolic Quadratic Forms	314
2.10	Reflection-Generated Discrete Groups in High-Dimensional Lobachevskian Spaces	315
	References	317